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// Haar transforms with coefficients normalized in L2-norm, i.e. {h_n} = {1/sqrt(2),
1/sqrt(2)};
template <typename T>
void L2_Haar_lifting_2D_transform(basic_matrix<T> &image, int M)
{
    // An L2 normalization constant
    T const sqrt_2 = std::sqrt(2.0);

    int image_size = image.height();
    for(int m = 0; m < M; ++m)
    {
        int const step = 1 << m;
        // row wise 1D transform
        for(int i = 0; i < image_size; ++i)
        {
            for(int j = 0; j < image_size; j += 2)
            {
                T &s = image[i * step][j * step],
                &d = image[i * step][(j + 1) * step];

                d -= s; // predicting a difference

                d /= sqrt_2;

                s *= sqrt_2;
                s += d; // updating a mean
            }
        }
        // column wise 1D transform
        for(int i = 0; i < image_size; ++i)
        {
            for(int j = 0; j < image_size; j += 2)
            {
                T &s = image[j * step][i * step],
                &d = image[(j + 1) * step][i * step];

                d -= s; // predicting a difference

                d /= sqrt_2;

                s *= sqrt_2;
                s += d; // updating a mean
            }
        }
        image_size >>= 1;
    }
}

// Haar transforms with coefficients normalized in L1-norm, i.e. {h_n} = {1/2, 1/2}
template <typename T>
void L1_Haar_lifting_2D_transform(basic_matrix<T> &image, int M)
{
    int image_size = image.height();
    // row wise 1D transform
    for(int m = 0; m < M; ++m)
    {
        int const step = 1 << m;
        for(int i = 0; i < image_size; ++i)
        {
            for(int j = 0; j < image_size; j += 2)
            {
                T &s = image[i * step][j * step],
                &d = image[i * step][(j + 1) * step];

                d -= s; // predicting a difference
                s += d/2; // updating a mean
            }
        }
    }
}

```

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// column wise 1D transform
for(int i = 0; i < image_size; ++i)
{
    for(int j = 0; j < image_size; j += 2)
    {
        T &s = image[j * step][i * step],
          &d = image[(j + 1) * step][i * step];

        d -= s;          // predicting a difference
        s += d/2;        // updating a mean
    }
}
image_size >>= 1;
}
```